ChE 152B

Winter, 2010

Lab 1: Model Development

Instructions for operation of pendulum simulation

IMPORTANT: FOLLOW THIS SEQUENCE OF EVENTS FOR EVERY PENDULUM SIMULATION

- 1. Open .mdl file in MATLAB (type the name at the command prompt)
- 2. Compile the model (CTRL + B)
- 3. Switch the power ON to the box
- 4. Connect to target in Simulink (Simulation \rightarrow Connect to target)
- 5. Press START on the box
- 6. Start the simulation (Simulation \rightarrow Start the real-time code)

SAVE ALL YOUR INTERMEDIATE DATA. BACKUP YOUR DATA IN THE DESKTOP FOLDER WITH YOUR GROUP'S NAME

- 1. Run the CartIdent simulation (type CartIdent at the command prompt)
- 2. Run the simulation as per the above instructions
 - a. Double-click on the simout block, to ascertain the sampling period
- 3. Detrend and assign the output data
 - a. u=detrend(simout(:,3));
 - b. y=detrend(simout(:,1));
- 4. Run the system identification toolbox (type ident at the command prompt)
 - a. Select Import data \rightarrow Time domain data
 - b. Specify the workspace variables (u, y) and the sampling period (0.05)
 - c. Specify the start time as 0
 - d. Drag the data into the Working Data box
 - e. Select Estimate \rightarrow Parametric Models
 - f. Choose your model type and order
 - g. Select Estimate
- 5. Drag the created model to the "To Workspace" box

NOTE: For exercise 6, you should only use the data collected when the pendulum is inverted, hence you should ignore the first half of the data collected